



Transilvania University of Brasov
Faculty of Silviculture and Forest Engineering

Mapping forest disturbances by combining Landsat image composites and Unmanned Aerial Systems

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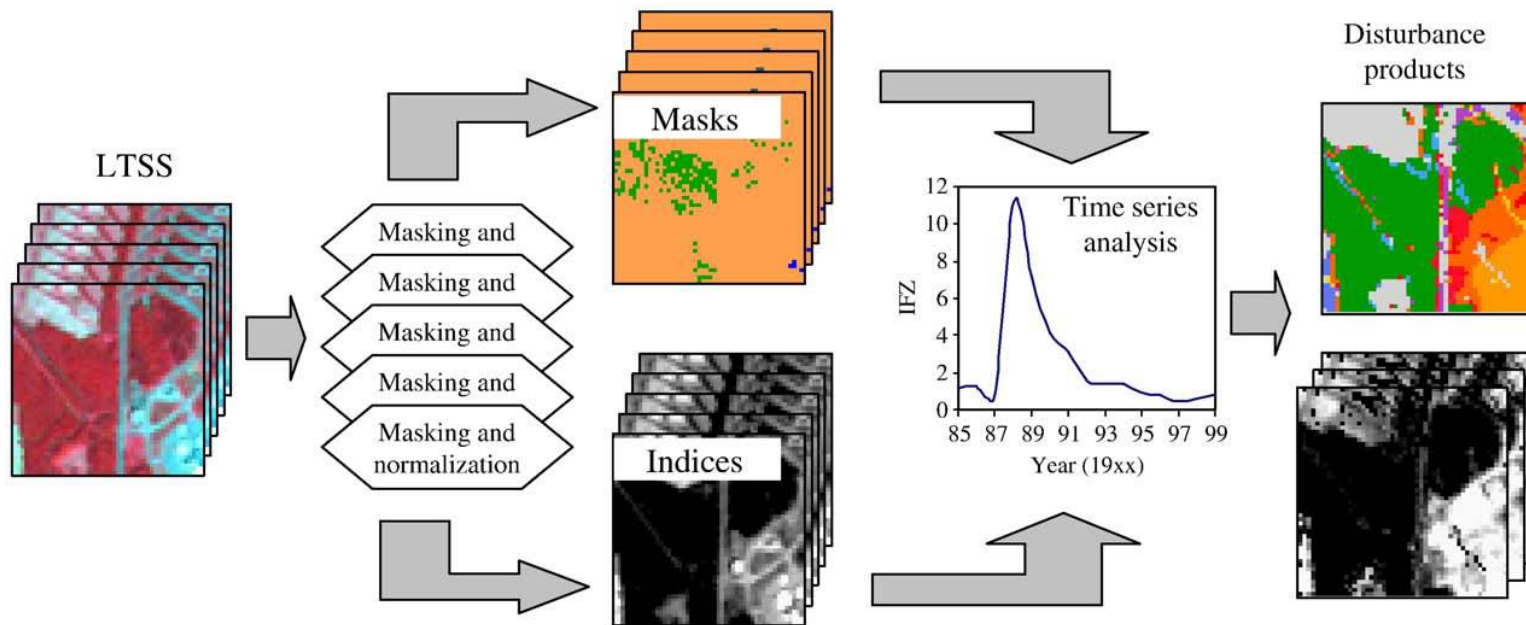
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Forest disturbances

- Forest **disturbance and recovery** are critical **ecosystem processes** and an improved monitoring of changes in forest structure is needed to quantify natural and human impact on forest systems.
- **Landsat's temporal and spatial coverage**, moderate spatial resolution, and long history of earth observations provide a unique opportunity for **characterizing vegetation changes.**

Forest disturbances

- On macro level, mapping forest disturbances with **Landsat** offers a **large view** on forest disturbances which occur during a **management** cycle.

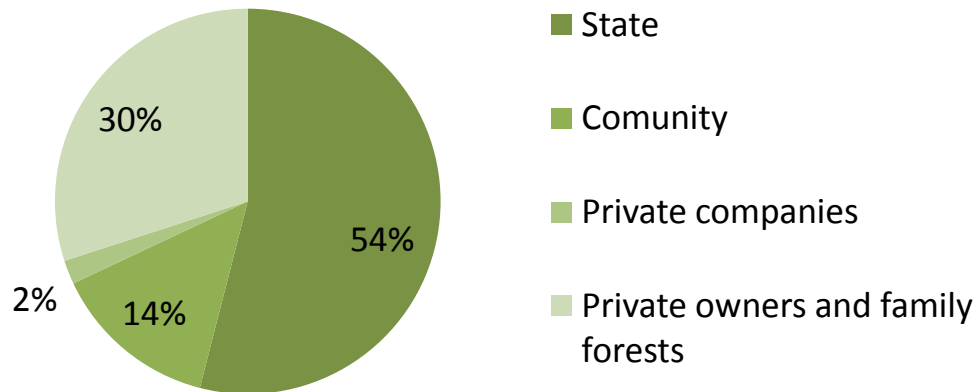


EXAMPLE: The Vegetation Change Tracker algorithm uses the spectral-temporal properties of Landsat Time Series Stacks to produce forest disturbance products (from Huang et al. - 2010)

Present context

- Where forestry in the past focused on the production of a few commodities, the **evolution to small scale forestry** demands that new ways of forest management and monitoring to be adopted.
- These methods should combine past knowledge with innovative management planning strategies and up-to-date technology.

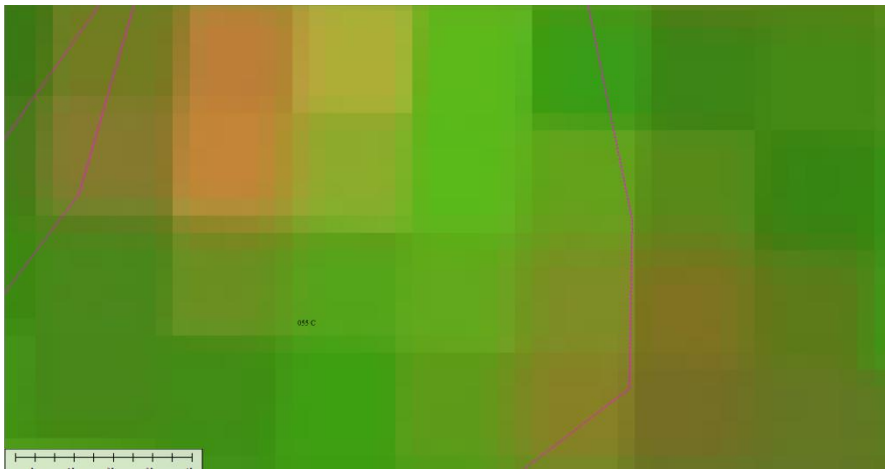
Forest ownership in Romania



Source: National Forest Inventory, 2013

Present context

- From manager point of view, mapping forest disturbances with Landsat does **not solve the entire problem**.
- The lack of information which Landsat low spatial resolution cannot provide related to the disturbance (e.g. windthrow vs. illegal logging, clear cut vs. final cut) makes the method less attractive.



Landsat low spatial resolution composite (30m/pixel)



UAS high spatial resolution (0.05 m/pixel)

Present context – Problem?

- Due to economical issues, in many cases, is preferred a more detailed analysis of the problem **using on-site observation**, than using a previous analysis based on high resolution remote sensing method.
- The forest managers need their information as fast and accurate it gets to take the decision
- The reason?.... **Not only the PRICE ... the lead time is a reason too.**

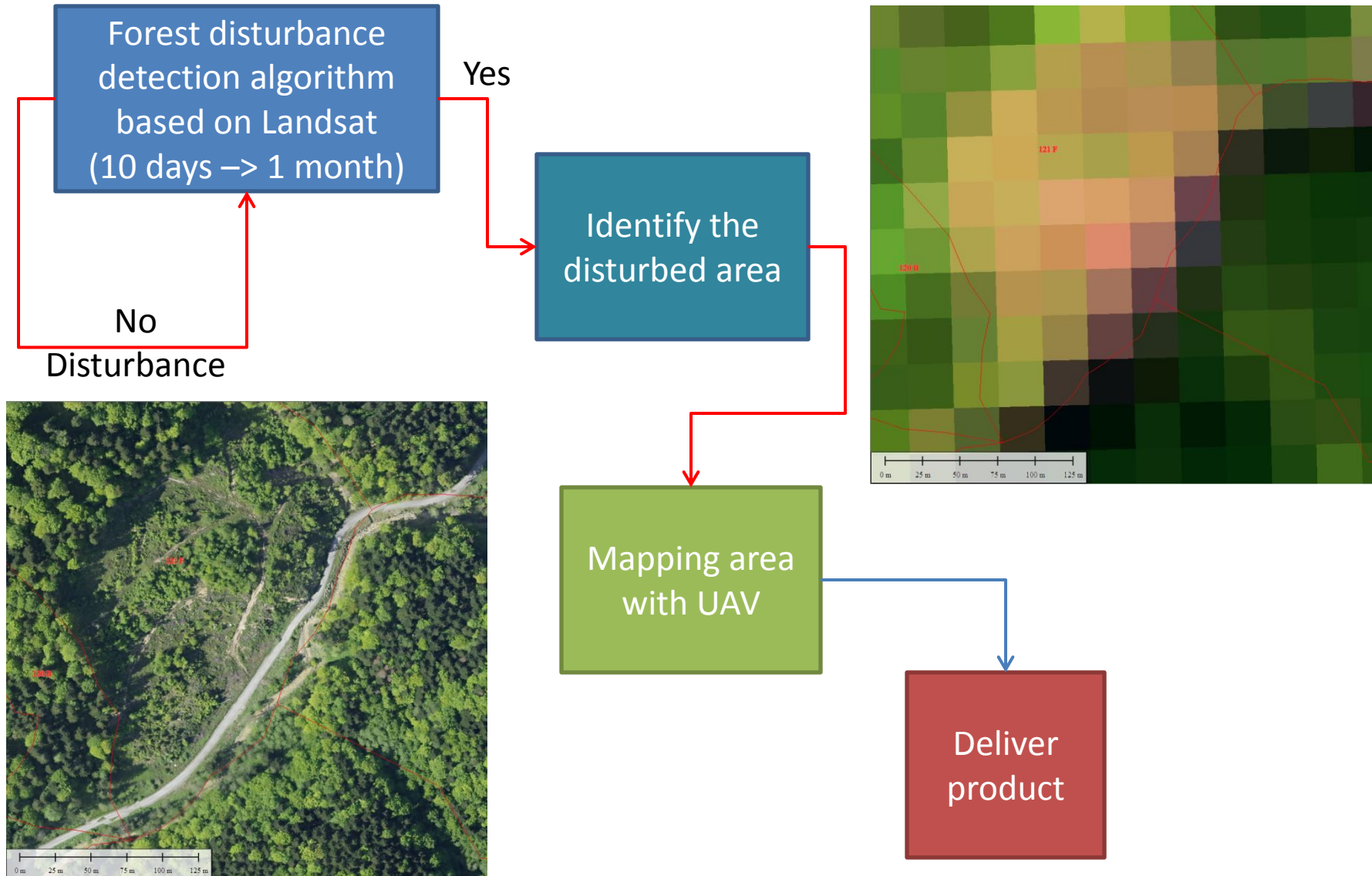
Satellite product	Price	Lead time
IKONOS (1m)	Minimum order = 2000 – 3600 \$	30 – 120 days
Digital Globe (0.6 m)	Minimum order = 1500\$	30 – 120 days
Worldview 2 (0.5)	Minimum order = 2200\$	30 – 120 days

Source: **Walsh Environmental Scientists and Engineers**

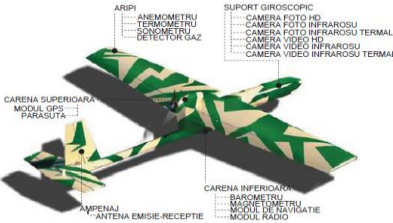
Present context – Solution?...UAV

- A product fast enough, accurate enough and cheaper enough to **serve small scale forest managers**
- Nowadays UAS (Unmanned Aerial Systems) technology is rapidly growing and extending. UAS make up the aerospace industry's most dynamic growth sector.
- According to a recent market study, UAV (Unmanned Aerial Vehicles) spending is on pace to double during the 2010 – 2020 period, from current worldwide expenditures of 4.3 billion euro annually to 8.2 billion euro, totalling just more **than 68 billion euro**.
- Although started as hobby for model plane enthusiasts, civil drone technology expanded especially in remote sensing area.
- The reasons are simple: **they are cheap, easy to use and offer high resolution products in short time**. Based on this, a high resolution remote sensing method becomes attractive to forest managers interested in mapping forest disturbances.

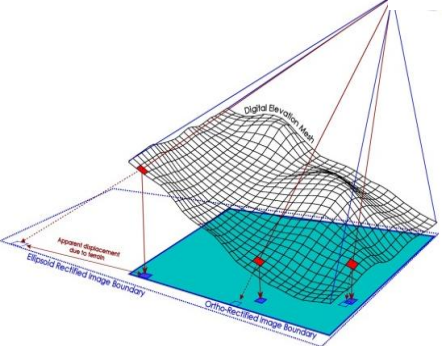
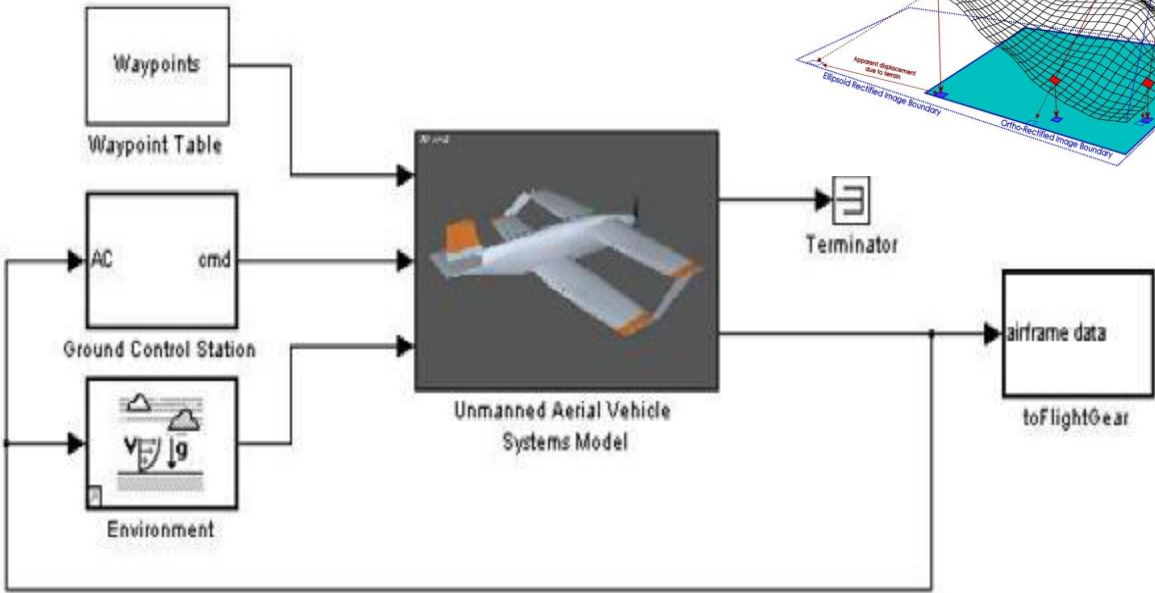
Methodology



UAS – Unmanned Aerial System

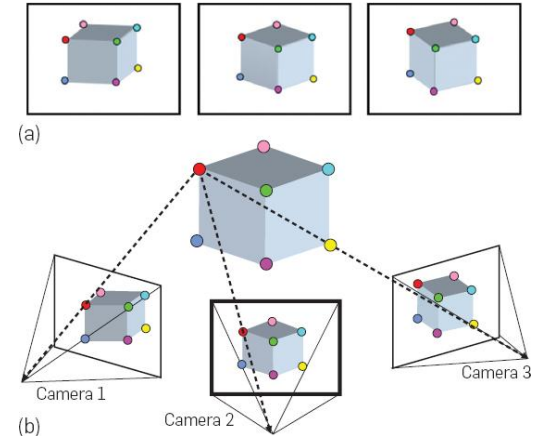


UAV Model and Simulation

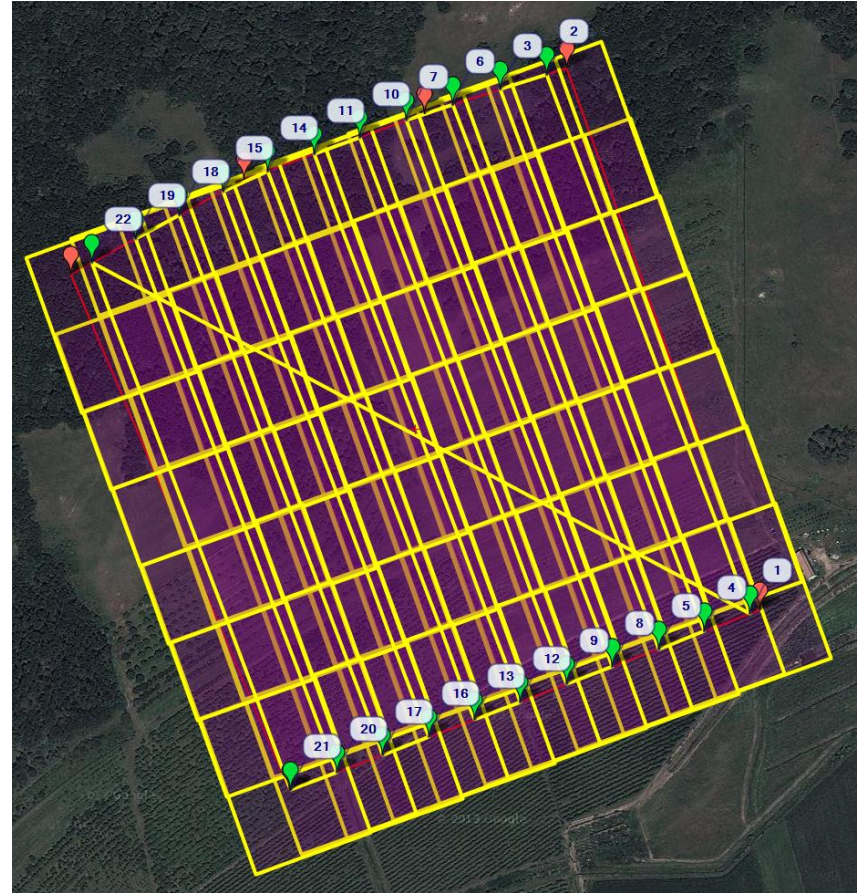
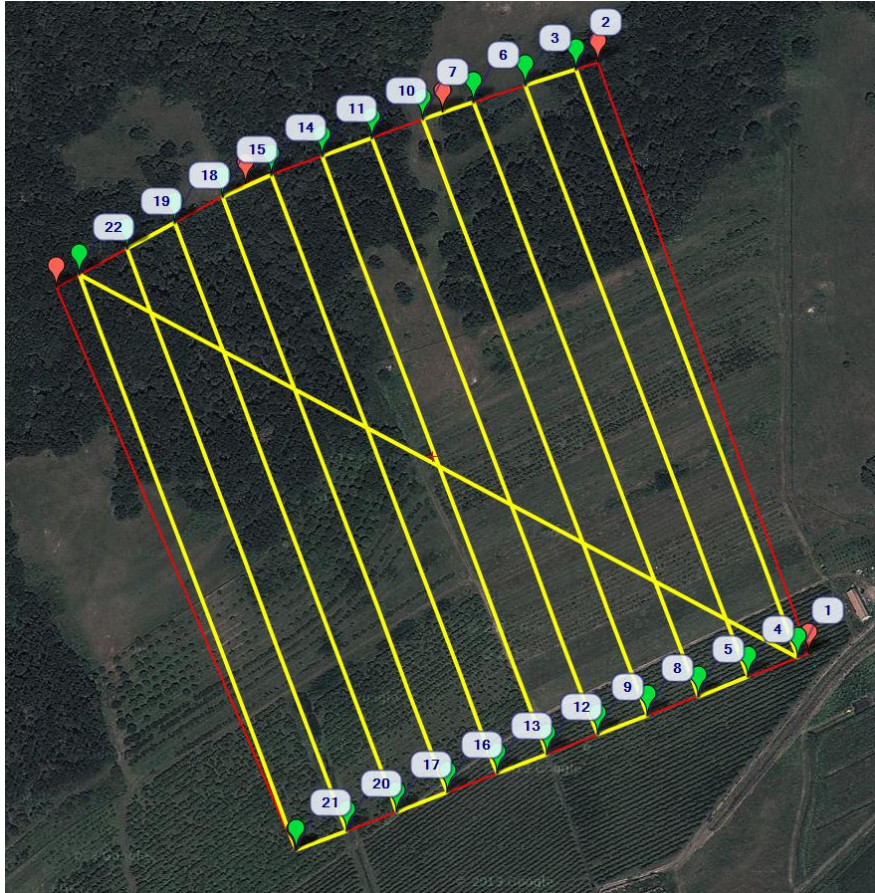


Steps in producing UAV data

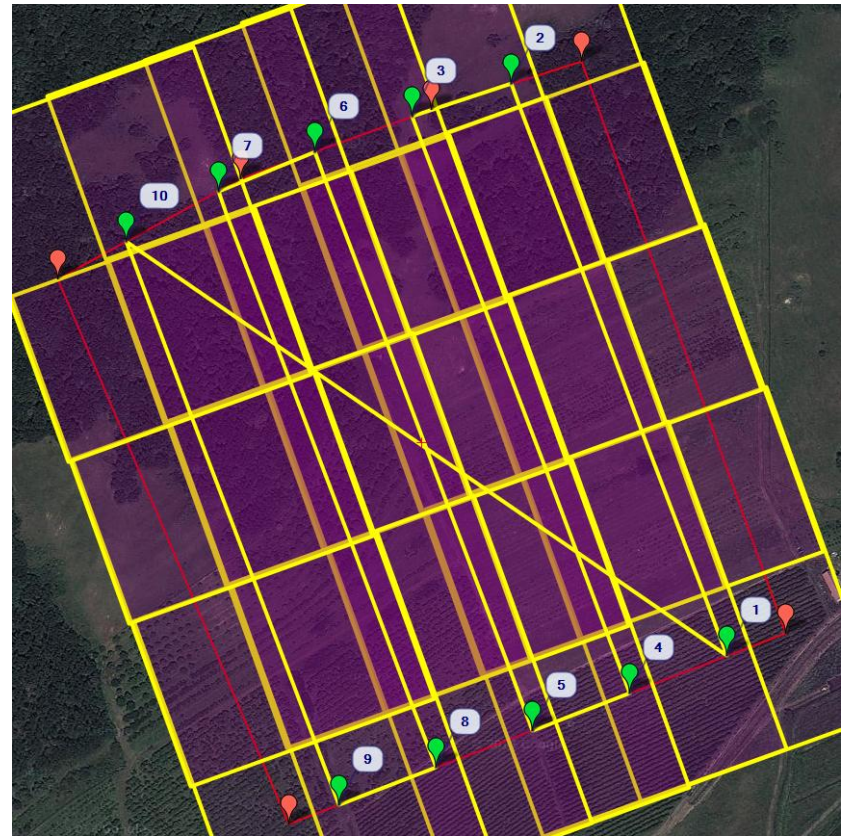
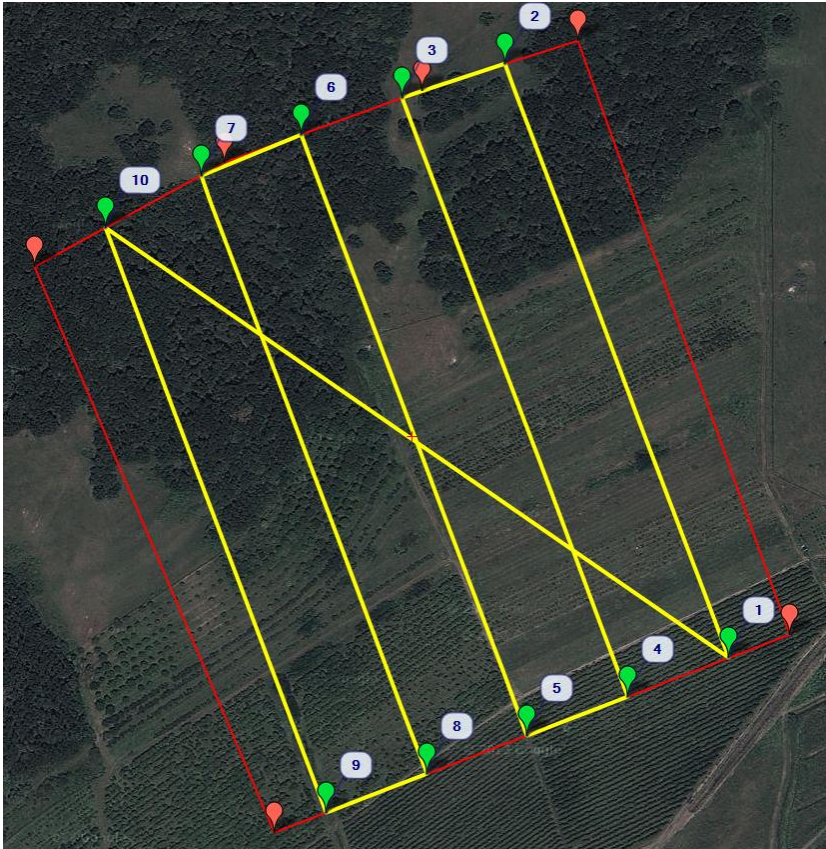
- Identifying the area
- Producing the Flight plan
- Data acquisition
- Data processing (Structure from Motion)
- Georeferencing
- Extracting the products



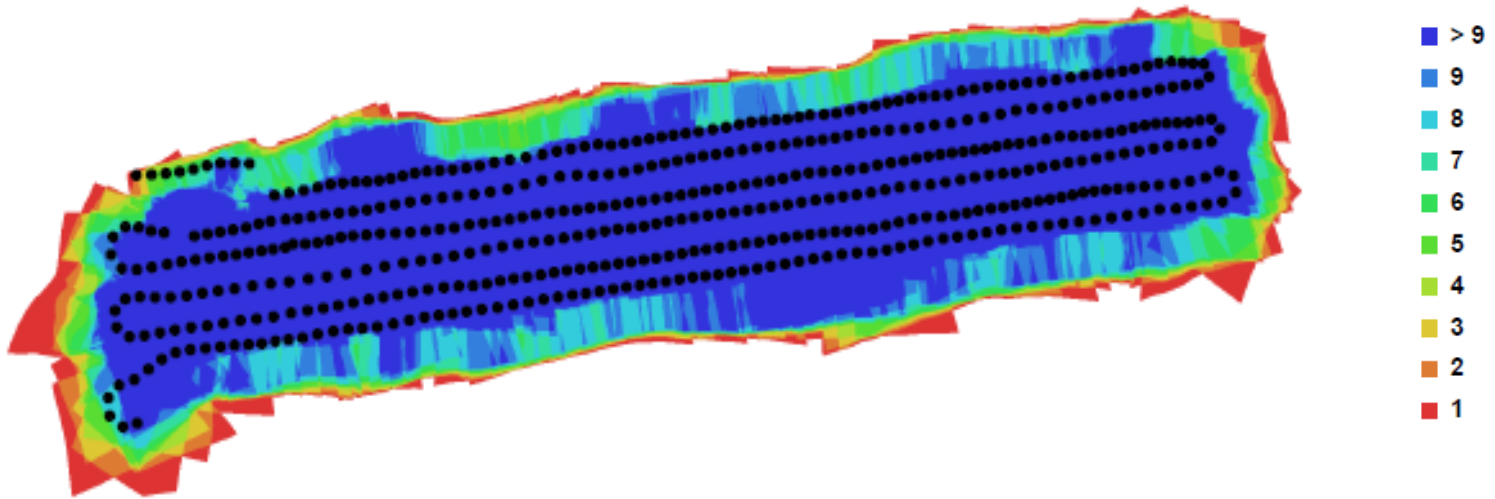
Flight plan



Flight plan



Data acquisition



Data processing

The screenshot displays a photogrammetry software interface with a 3D point cloud model of a road. The model is populated with numerous camera positions, represented by blue and red squares, and ground control points, represented by yellow dots. The camera positions are labeled with filenames such as DSC_0124.JPG, DSC_0125.JPG, DSC_0126.JPG, DSC_0127.JPG, DSC_0128.JPG, DSC_0129.JPG, DSC_0130.JPG, DSC_0131.JPG, DSC_0132.JPG, and DSC_0133.JPG. The ground control points are labeled with names like point 16, point 19, point 18, point 8, point 7, point 5, point 23, point 3, point 4, and point 1. The software interface includes a 'Workspace' panel on the left, a 'Ground Control' panel with a table of camera and marker data, a 'Scale Bars' panel, and a 'Photos' panel at the bottom. A 'Free license (non-commercial use only)' dialog box is also visible in the bottom left corner.

Workspace (1 chunks, 397 cameras)
Chunk 1 (397 cameras, 31 markers, 885717 points) [R]

Ground Control

Cameras	Longitude	Latitude	Altitude	Error (m)	Yaw
<input checked="" type="checkbox"/> DSC_0124.JPG	26.461944	46.940278	641.000000		
<input checked="" type="checkbox"/> DSC_0125.JPG	26.459167	46.940000	652.000000		
<input checked="" type="checkbox"/> DSC_0126.JPG	26.459167	46.940000	652.000000		
<input checked="" type="checkbox"/> DSC_0127.JPG	26.456389	46.940000	645.000000		
<input checked="" type="checkbox"/> DSC_0128.JPG	26.453889	46.940000	656.000000		
<input checked="" type="checkbox"/> DSC_0129.JPG	26.453889	46.940000	656.000000		
<input checked="" type="checkbox"/> DSC_0130.JPG	26.451111	46.940000	665.000000		
<input checked="" type="checkbox"/> DSC_0131.JPG	26.448333	46.939722	667.000000		
<input checked="" type="checkbox"/> DSC_0132.JPG	26.448333	46.939722	667.000000		
<input checked="" type="checkbox"/> DSC_0133.JPG	26.445556	46.939444	659.000000		

Markers	Longitude	Latitude	Altitude	Error (m)	Projections	Err
<input checked="" type="checkbox"/> point 16	26.444314	46.871854	296.388000	229.166407	3	
<input type="checkbox"/> point 19	26.439904	46.884872	301.077000	151.626531	2	
<input type="checkbox"/> point 18	26.447040	46.875023	296.374000	127.333327	3	
<input type="checkbox"/> point 8	26.432237	46.884495	303.179000	87.364716	3	
<input type="checkbox"/> point 7	26.426911	46.887761	305.631000	55.277115	4	
<input type="checkbox"/> point 5	26.427311	46.890561	304.940000	47.798199	3	
<input type="checkbox"/> point 23	26.427162	46.895041	306.413000	46.714267	3	
<input type="checkbox"/> point 3	26.423917	46.893043	307.202000	33.330029	4	
<input type="checkbox"/> point 4	26.421333	46.891809	305.716000	29.878193	5	
<input type="checkbox"/> point 1	26.416668	46.896668	309.578000	25.231099	5	

Scale Bars Distance (m) Error (m)

Total Error

Free license (non-commercial use only)

Session list

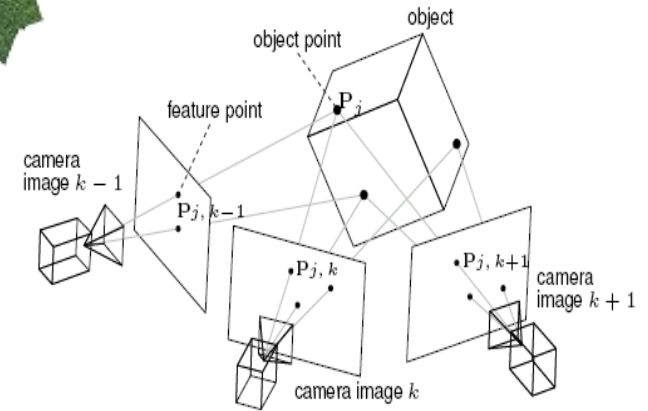
779 318 214

www.teamviewer.co

Photos

Console

Georeferencing – ground control points



Label	X error (m)	Y error (m)	Z error (m)	Error (m)	Projections	Error (pix)
point 1	0.007806	-0.016210	0.025177	0.030945	11	1.106495
point 2	-0.012901	0.014468	-0.168445	0.169557	6	2.113992
point 3	-0.019241	-0.021600	-0.065353	0.071469	13	0.505121
point 4	0.033561	0.041795	0.192248	0.199581	7	0.548978

Georeferencing

BEFORE using ground control points

Markers	Longitude	Latitude	Altitude	Error (m) ▾	Projections	Err ▲
<input type="checkbox"/>	point 16	26.444314	46.871854	296.388000	229.166407	3
<input type="checkbox"/>	point 19	26.439904	46.884872	301.077000	151.626531	2
<input type="checkbox"/>	point 18	26.447040	46.875023	296.374000	127.333327	3
<input type="checkbox"/>	point 8	26.432237	46.884495	303.179000	87.364716	3
<input type="checkbox"/>	point 7	26.426911	46.887761	305.631000	55.277115	4
<input type="checkbox"/>	point 5	26.427311	46.890561	304.940000	47.798199	3
<input type="checkbox"/>	point 23	26.427162	46.895041	306.413000	46.714267	3
<input checked="" type="checkbox"/>	point 3	26.423917	46.893043	307.202000	33.330029	4
<input checked="" type="checkbox"/>	point 4	26.421333	46.891809	305.716000	29.878193	5
<input type="checkbox"/>	point 1	26.416868	46.896683	309.578000	25.231909	5

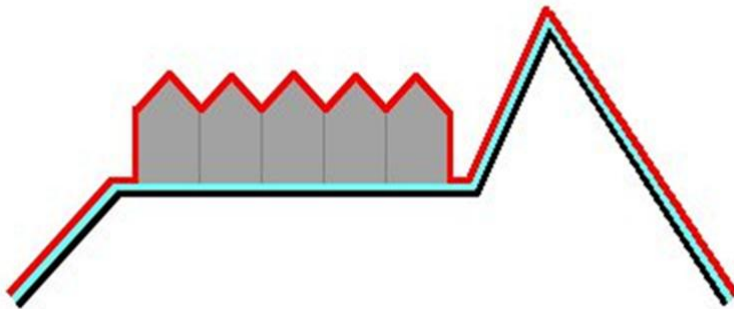
AFTER using ground control points



Markers	Longitude	Latitude	Altitude	Error (m) ▾	Projections	Err ▲
<input type="checkbox"/>	point 7	26.426911	46.887761	305.631000	2.642843	4
<input checked="" type="checkbox"/>	point 5	26.427311	46.890561	304.940000	1.089449	3
<input checked="" type="checkbox"/>	point 1	26.416868	46.896683	309.578000	1.015263	5
<input checked="" type="checkbox"/>	point 2	26.418905	46.894747	308.517000	0.700830	5
<input checked="" type="checkbox"/>	point 3	26.423917	46.893043	307.202000	0.534738	4
<input checked="" type="checkbox"/>	point 4	26.421333	46.891809	305.716000	0.443556	5
<input type="checkbox"/>	point 21					3
<input type="checkbox"/>	point 20					
<input type="checkbox"/>	point 22					
<input type="checkbox"/>	point 24					

Results

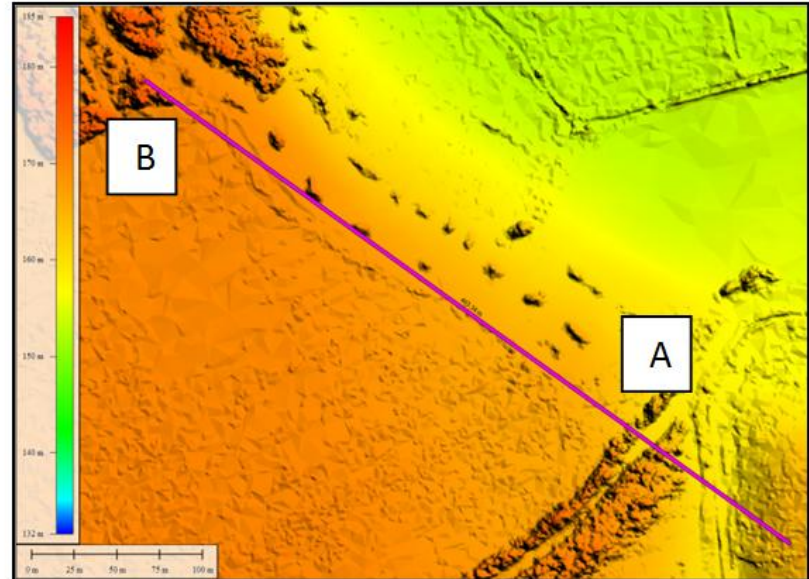
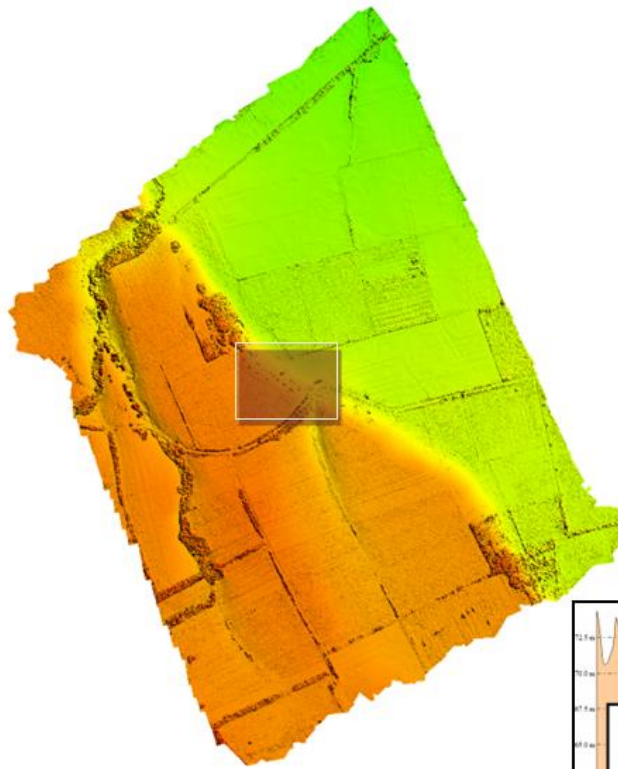
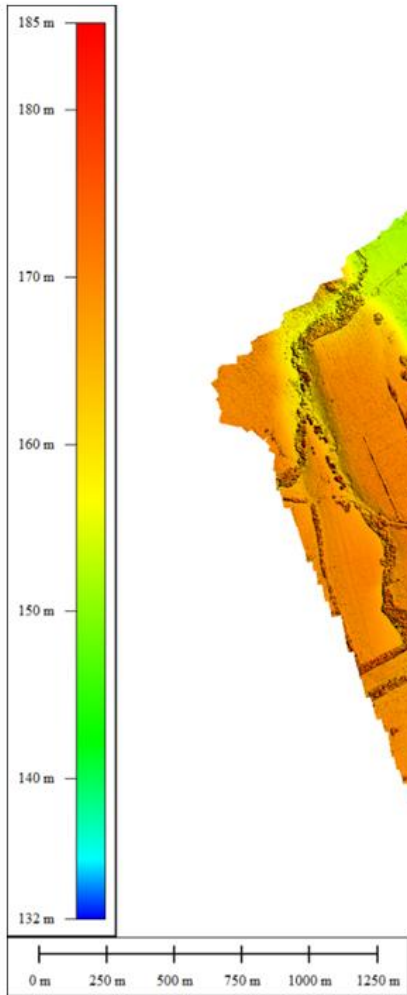
Ortoctified mosaic

Digital Surface Model (DSM)



	Digital Surface Model
	Digitale Terrain Model

Digital surface model



Examples



CASE STUDY: LUGOJ. Covered Area 15 square kilometers

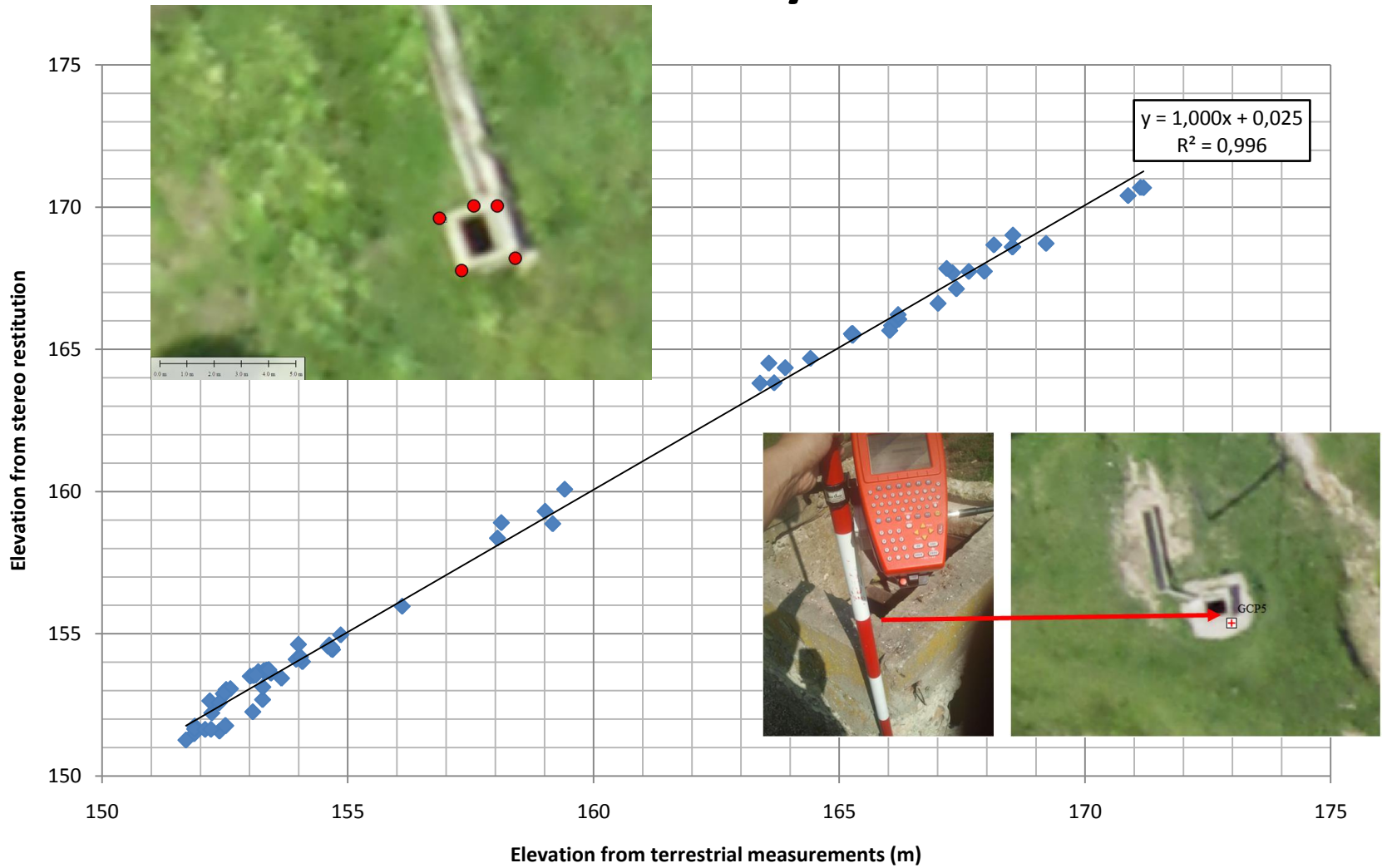
RESULTS

Synthetic data

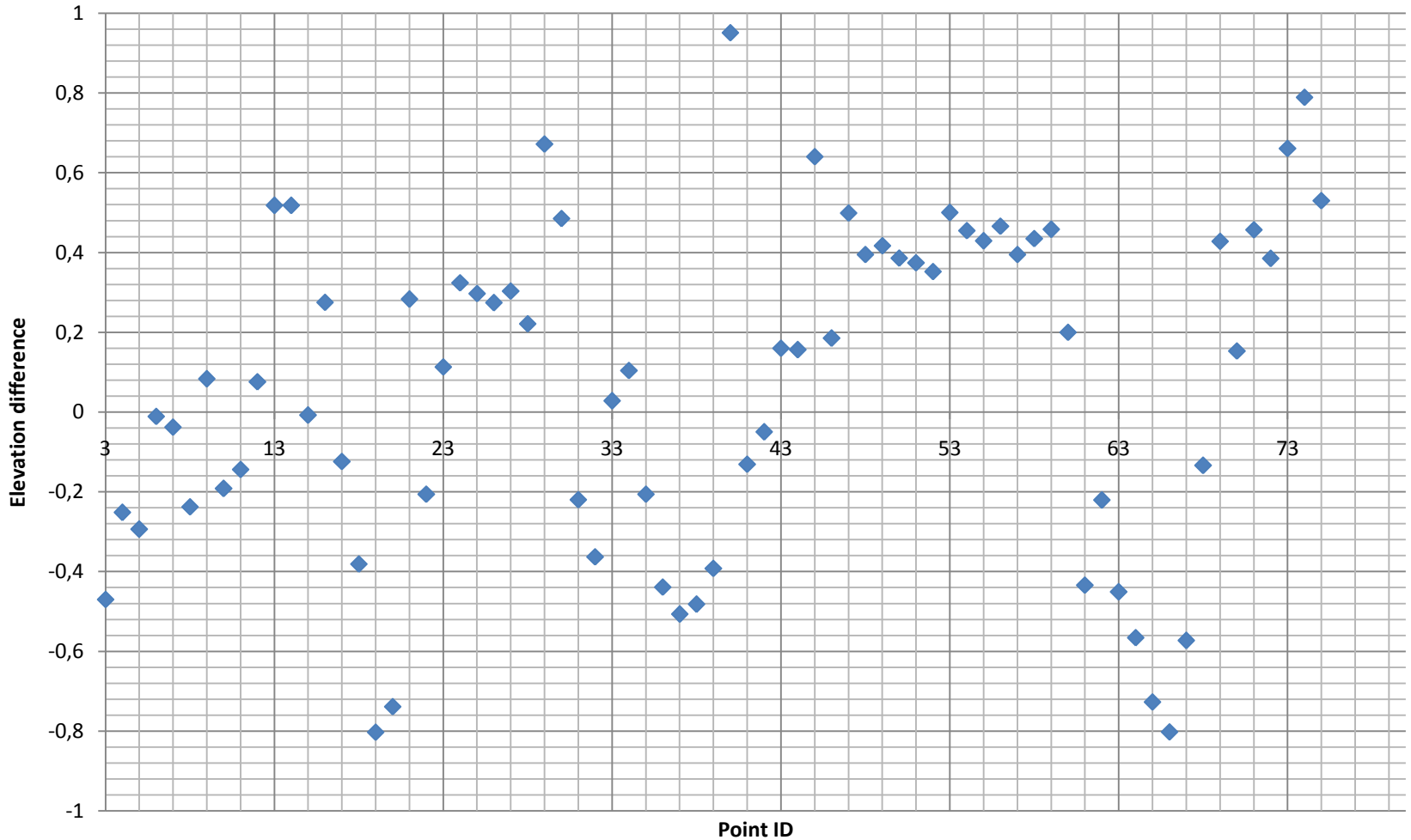
- Flight area: 1500 hectares
- Flight time: 1 day
- Data processing: 3 days
- Georeferencing: 1 day
- Flight Costs: 80 euro

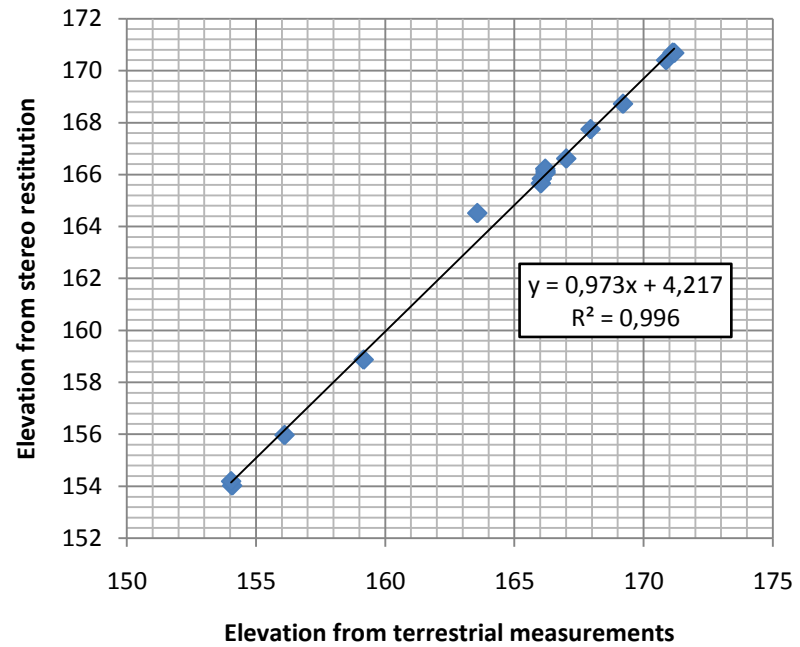
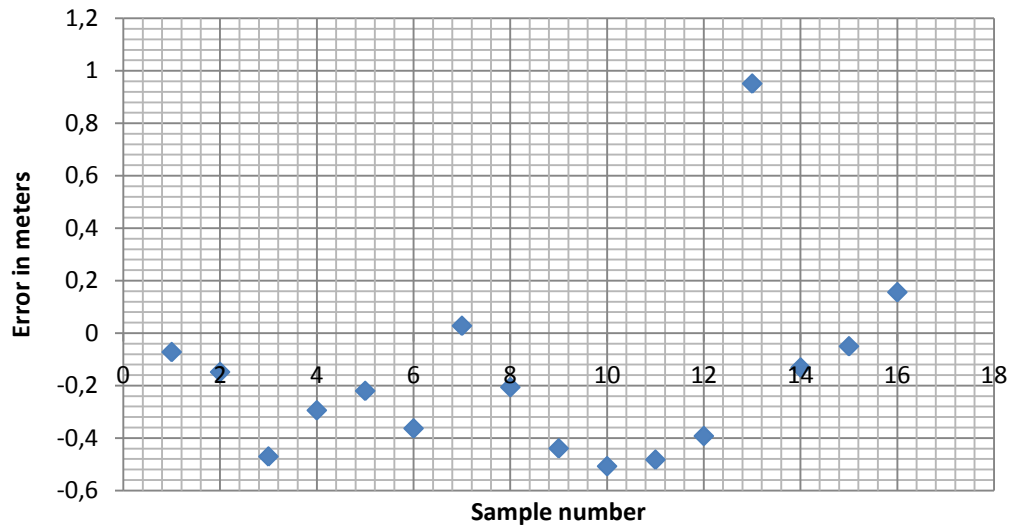
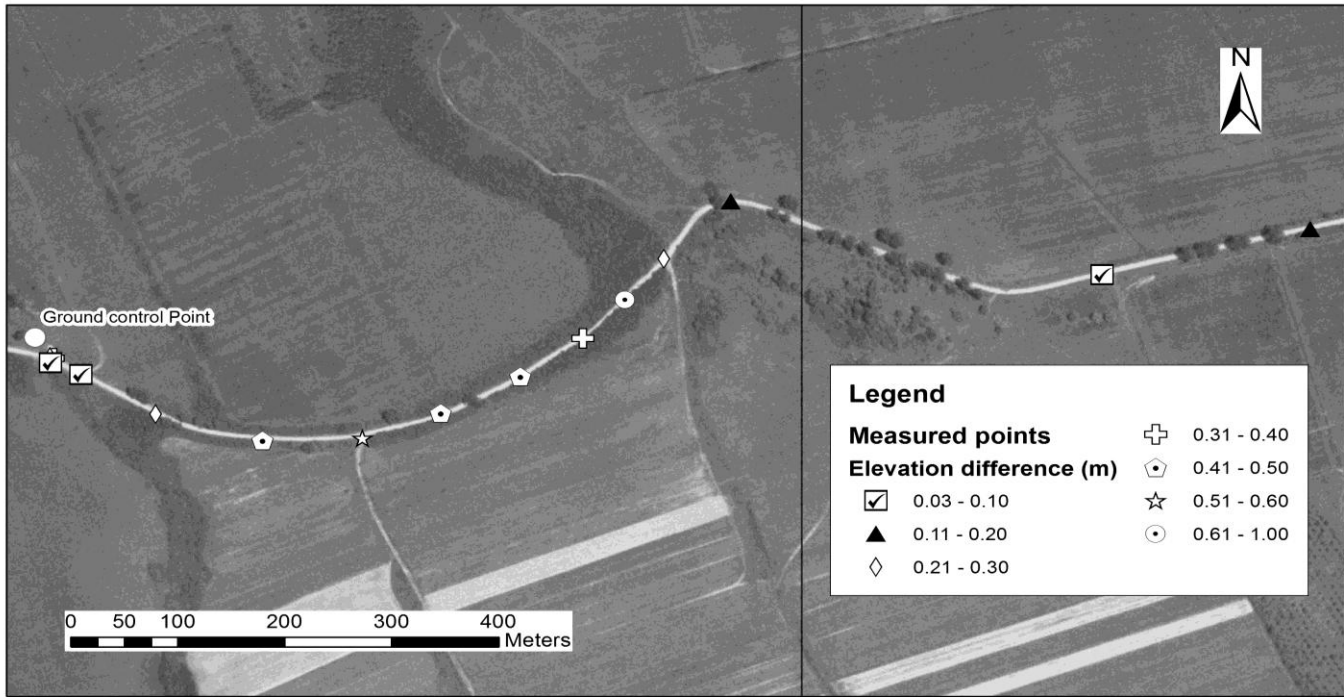


Accuracy



Elevation precision



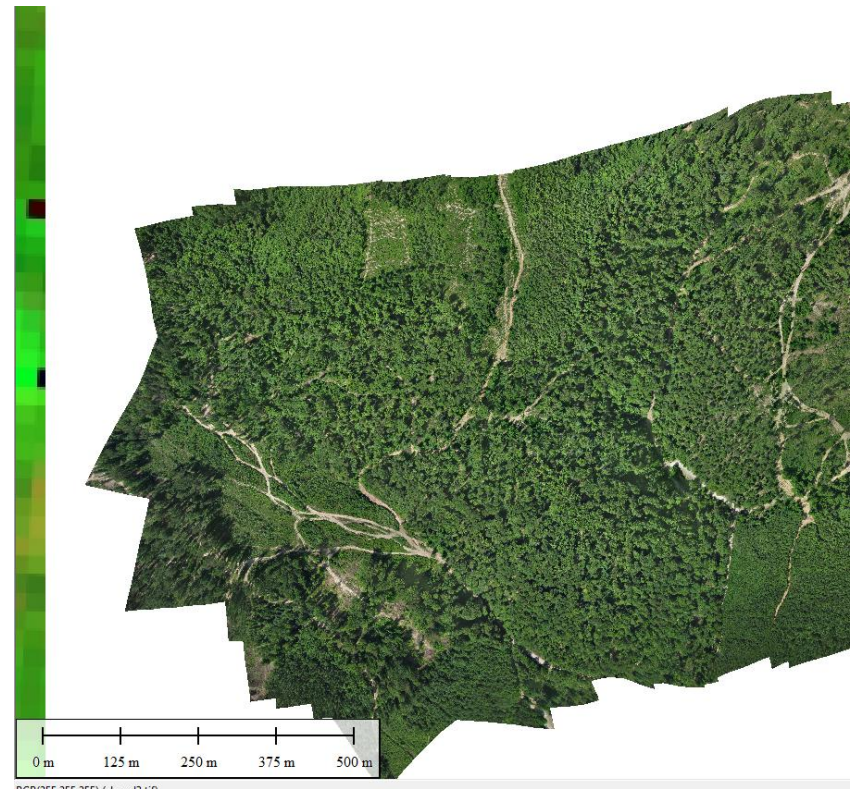


CASE STUDY: Dobrești. Covered area 30 square kilometers

RESULTS

Synthetic data

- Flight area: 3000 hectares
- Flight time: 2 day
- Data processing: 3 days
- Georeferencing: 1 day
- Flight Costs: 160 euro

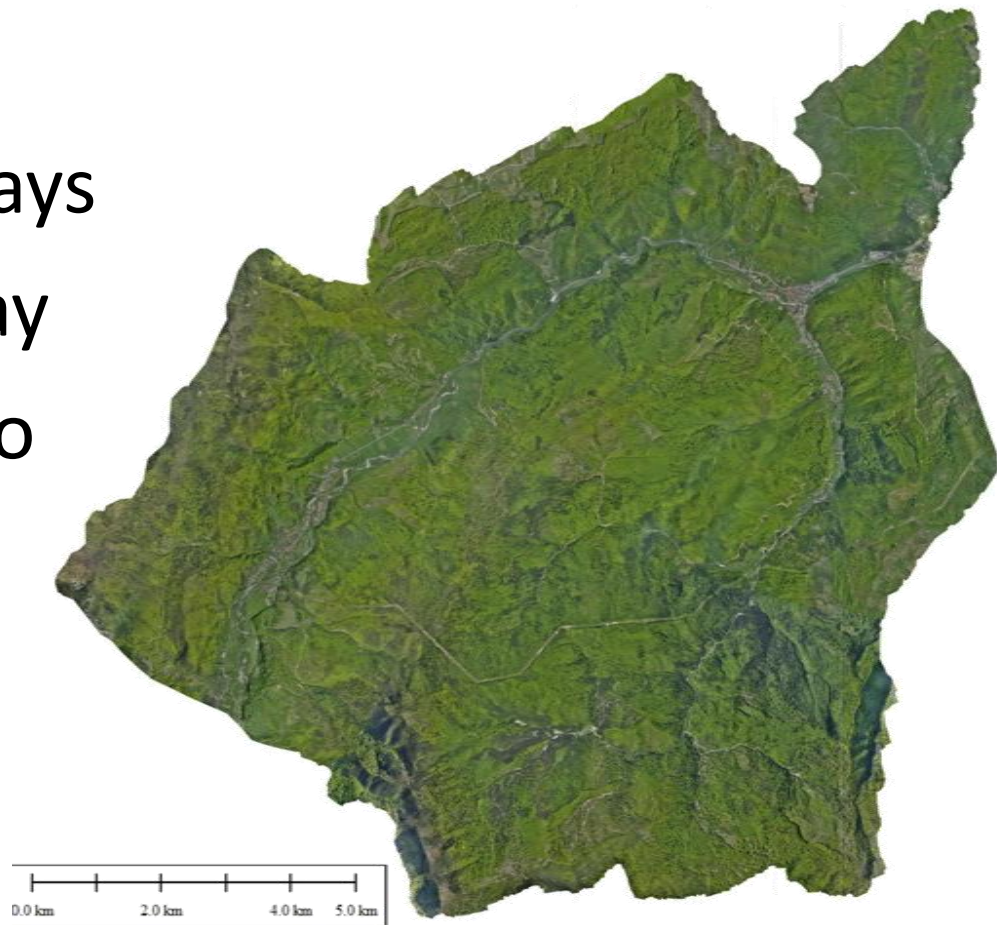


CASE STUDY: OITUZ. Covered area 100 square kilometers

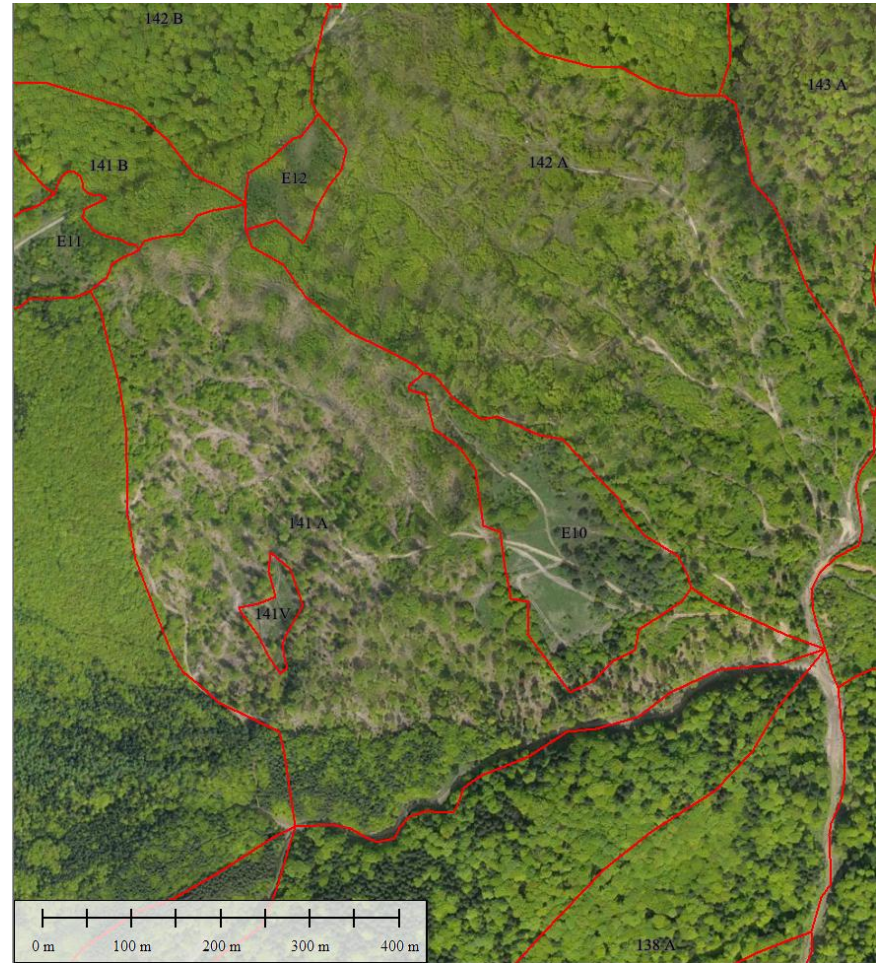
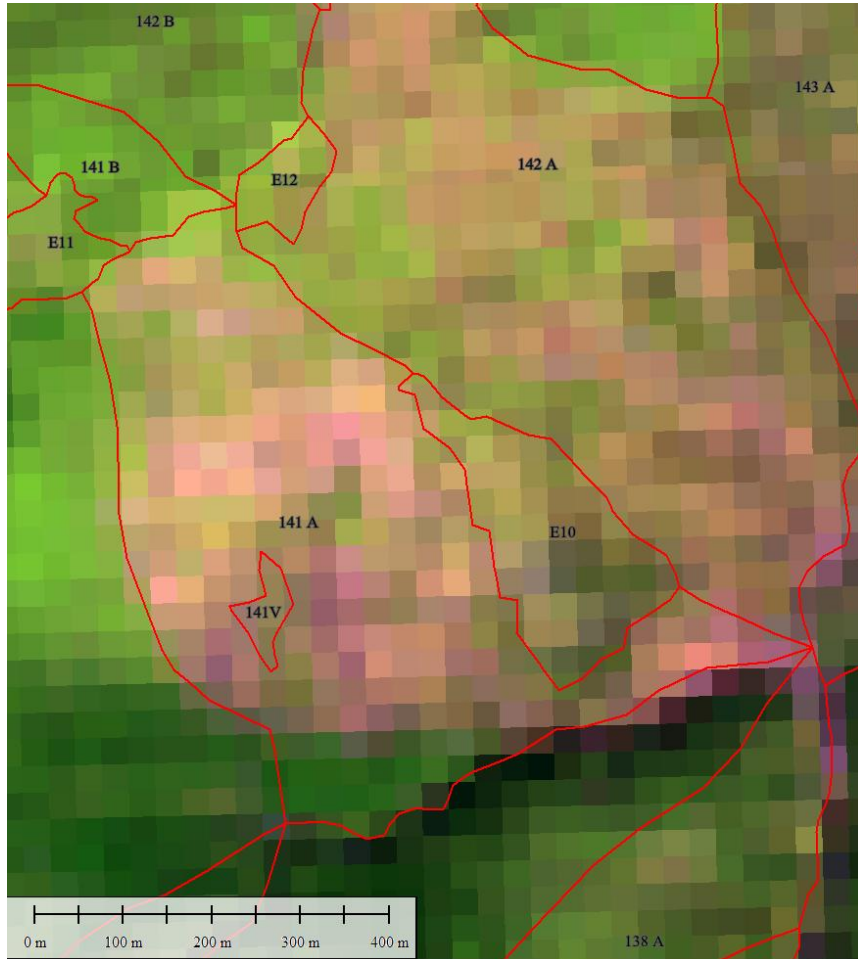
RESULTS

Synthetic data

- Flight area: 10000 hectares
- Flight time: 4 days
- Data processing: 6 days
- Georeferencing: 1 day
- Flight Costs: 600 euro



Examples



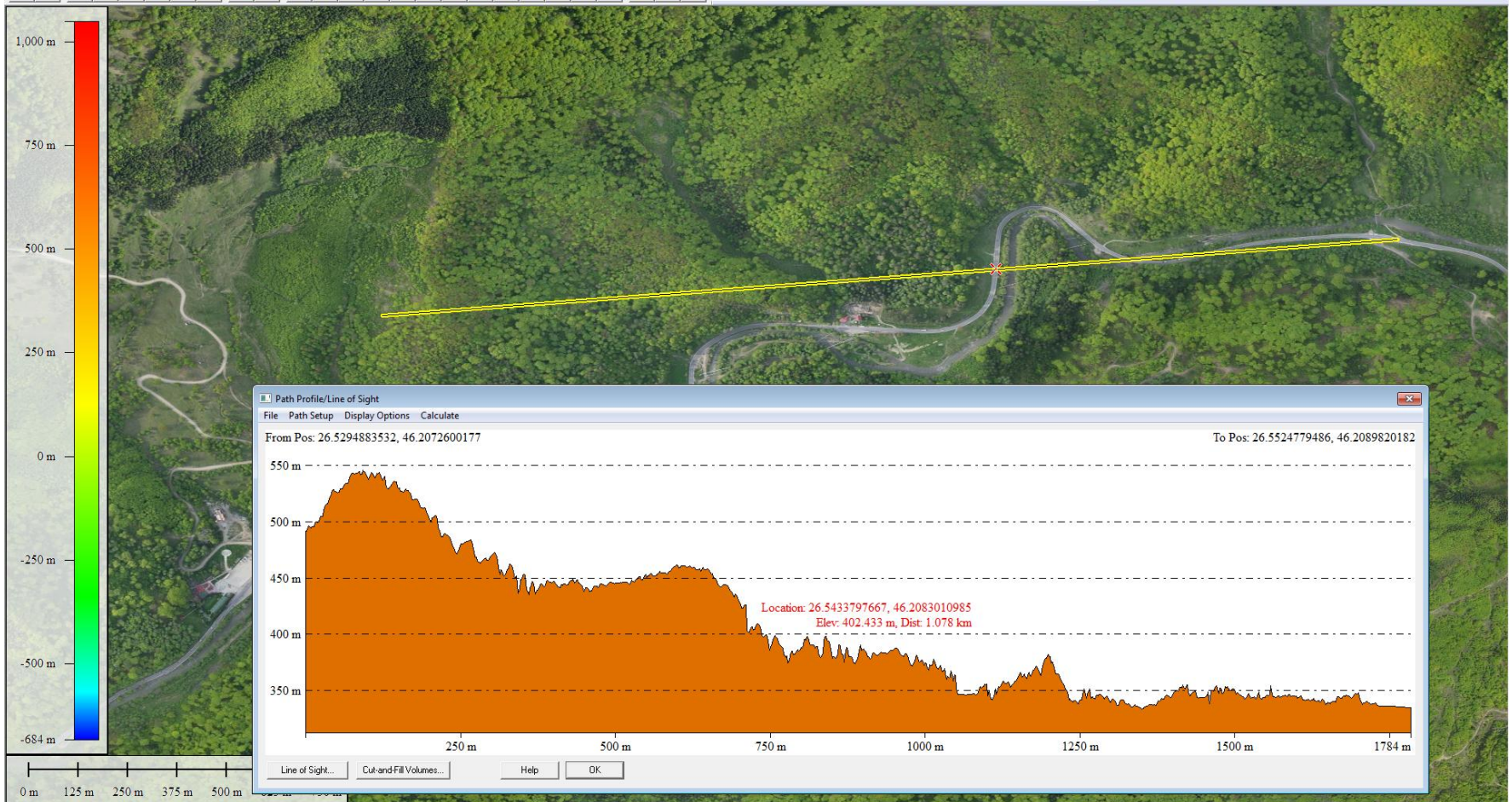
Examples



Examples



Examples – Digital Surface Model



Conclusions

- UAS technology of taking photos with UAV and obtaining complex info as digital surface model and orthorectified mosaic represents an **innovative methodology**
- The technology offers rapid response (few days) on quite large areas (400 hectares/hour)
- The costs of producing data are lower than the actual market

Conclusions

Start-up

UAV: 5k – 70k Euro

Pilot training: 1000 euro

Processing computer: 2000 euro

Total : starting from **10000 euro**

Thank you for attention!